

Linear motor data PPU-E35-Y-Axis for not Schunk supported controllers

Type of motor: PPU-E35-Y-Axis

Date of creation: 12.12.2023

Description	Symbol	Unit	Value
Daten			
Nominal motor force	F _{nenn}	N	147
Motor peak force	F _{max.}	N	400
Motor idle current (eff.)	I _{nenn}	A _{eff}	1,8
Motor peak current (eff.)	I _{max.}	A _{eff}	8
Max. velocity	V _{max.}	m/s	4
Power loss	P	W	250
Force constant	k _{Force}	N/A	82
Motor constant	k _{Motor}	N/√W	9,3
BEMF (velocity 1 m/s)	k _{EMK}	Vs/m	110
Thermal time constant	k _{therm.}	s	1200
Resistance	R _{phase / phase}	Ohm	22,30
Inductance	Lu-v, Lv-w, LW-u	mH	250,00
Number of pole pairs per distance		mm	28,1
Mass primary part	m _{Prim.}	kg	5
Mass Rail	m _{Sek.}	kg/m	0
Max. intermediate circuit voltage	U _{DC}	V	900
Max. coil temperature	T _{max.}	°C	90
Type of temperature sensor			KTY

Control parameters

Current loop propotional gain		V/A	417
Current loop integral action time		ms	14,0
Position loop KV-Factor	kv	1000/min	1
Velocity loop smoothing time const.		us	900
Velocity loop propotional gain	kp	N/(mm/min)	0,012
Velocity loop integral action time	TN	ms	5

Encoder Feedback

Type	magnetic	magnetic absolut	optical	magnetic absolut
Sensor designation	LE100	TTK 70	LIA 22	MSA111C
Tape measure	MB100	MBA 111	SINGLEFLEX DOUBLEFLEX	MBA 111
Manufactur	SIKO	Sick Stegmann	NUMERIK	Siko
Grating period	1000 µm	1000 µm	20 µm	1000 µm
Supply voltage	5 V	7V- 12V	5 V	4,5V - 30V
Waveform	sin/cos	sin/cos / Hiperface	sin/cos	sin/cos / SSI
Reference mark	periodic	--	periodic	--
Reference mark pitch	20 mm	--	50 mm	--
Signal amplitude	1 Vss	1 Vss	1 Vss	1 Vss
Feedback revolution	1 mm	1 mm	0,02 mm	1 mm

Motor connection

Connector	Anschluss	Stecker
Interconnectron Typ: LEAB08AN	U	thick 1
	V	thick 4
	W	thick 3
	GND	thick 2
3*temperature switch with KTY	Switch 105 °C ;	thin C
	PT1000	thin D

Thermal motor protection

	Sensor 1	Sensor 2
Type	NTC	Switch
Type	PT1000	normally closed
Characteristic	Datasheet	105 °C

Measurement system

	LE100	TTK 70	LIA 22	MSA111C
	Sub D pin	Sub D pin	Sub D pin	Sub D pin
Signal	Pin	Pin	Pin	Pin
0V Sense	15			
Ref - / EncData-	10	8	4	3
Ref + / EncData+	9	7	12	2
/B (COS-)	6	6	6	8
B(COS+)	5	5	14	9
A(SIN+)	2	2	13	7
/A(SIN-)	3	3	5	6
N.C.				
GND (0V)	4	4	9	12
N.C.				
Ucc	12	11	8	5
N.C.				
GND (Schirm)				
N.C.				

